

北大低温研・研究集会

干渉計解析の概要

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Interferometer in radio (1D): Each antenna obtains “E-field” information

Cross correlation for $\delta\phi$ direction

$$|E(\delta\phi)|^2 \exp\left(+i2\pi \frac{D}{\lambda} \delta\phi\right)$$

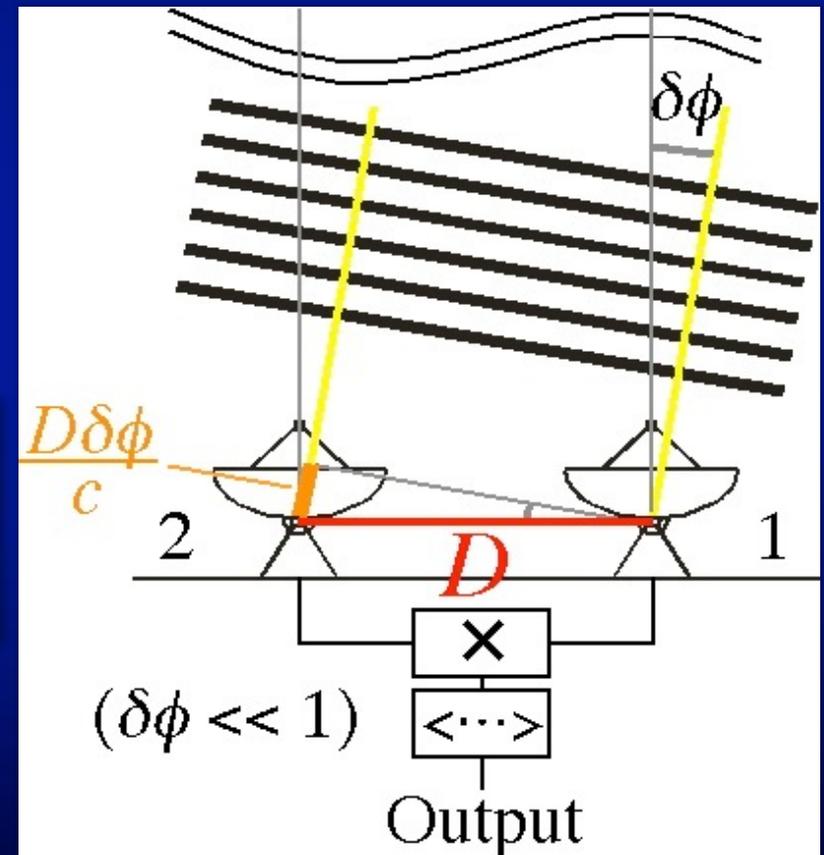
Integrating all the directions

$$V(D) = \int T(\delta\phi) \exp\left(+i2\pi \frac{D}{\lambda} \delta\phi\right) d(\delta\phi)$$

$V(D)$ is a Fourier component of $T(\delta\phi)$

→ Image can be reconstructed by data from many baselines

when the delay is adjusted to the zenith ...



Visibility and Brightness in 2D

Definition of “uv vector” for a projected baseline

$$\vec{D} = (D_u, D_v) \equiv \lambda(u, v)$$

(u, v) は地面, (x, y) は天球。 $u \parallel x$ は東西, $v \parallel y$ は南北

Fourier Transform between Visibility and Sky Brightness

$$V(u, v) = \iint T(x, y) e^{+i2\pi(ux+vy)} dx dy$$

$$T(x, y) = \iint V(u, v) e^{-i2\pi(ux+vy)} du dv$$

In reality, (1) antenna power pattern and (2) uv-sampling also affect the obtained data ...

$$(1) \quad \frac{V(u, v)}{\text{(得られる
ビジビリティ)}} \Leftrightarrow \frac{P(x, y)}{\text{(パワーパターン)}} \frac{T(x, y)}{\text{(真の輝度分布)}}$$

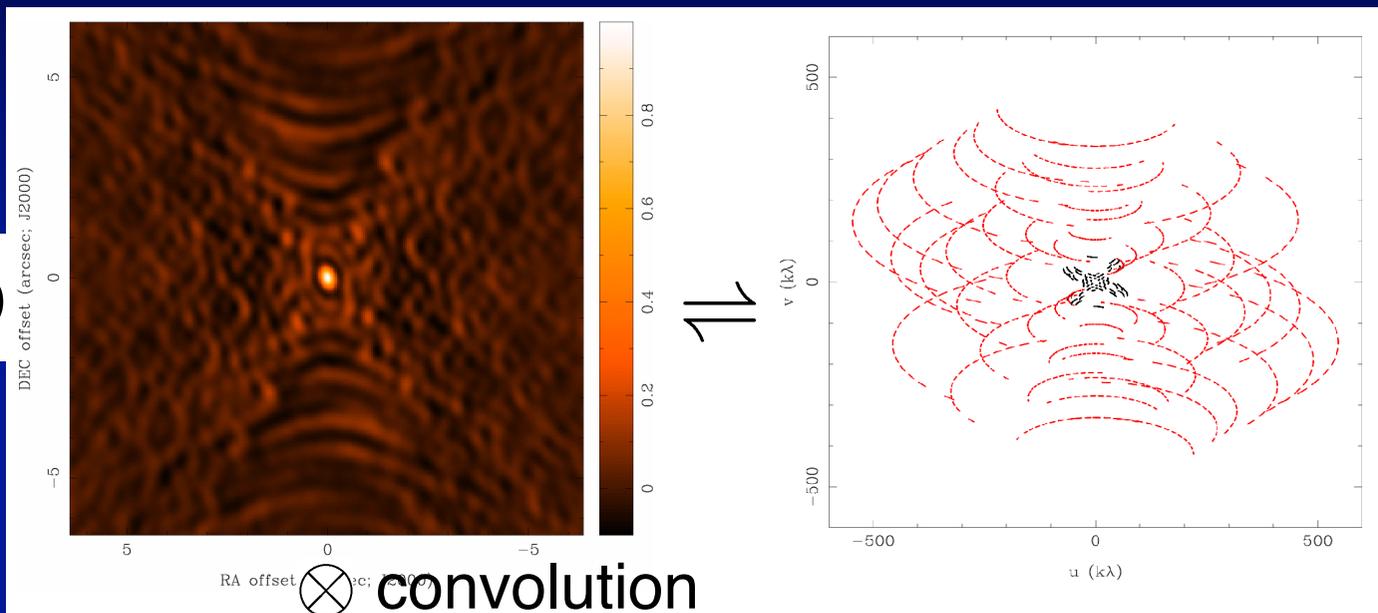
※パワーパターンは測定可能な量

$$(2) \quad \frac{P(x, y) T_{\text{dirty}}(x, y)}{\text{(直接出るマップ= Dirty Map)}} \\ = \iint \frac{[S(u, v) V(u, v)]}{\text{(標本関数 or 重み関数)}} e^{-i2\pi(ux+vy)} \, dudv \\ = \frac{B(x, y)}{\text{(Dirty Beam)}} * \frac{[P(x, y) T(x, y)]}{\text{(求めたい輝度分布)}} \\ \text{where } S(u, v) \Leftrightarrow B(x, y)$$

※関数積のフーリエ変換 = 各関数のフーリエ変換の畳み込み

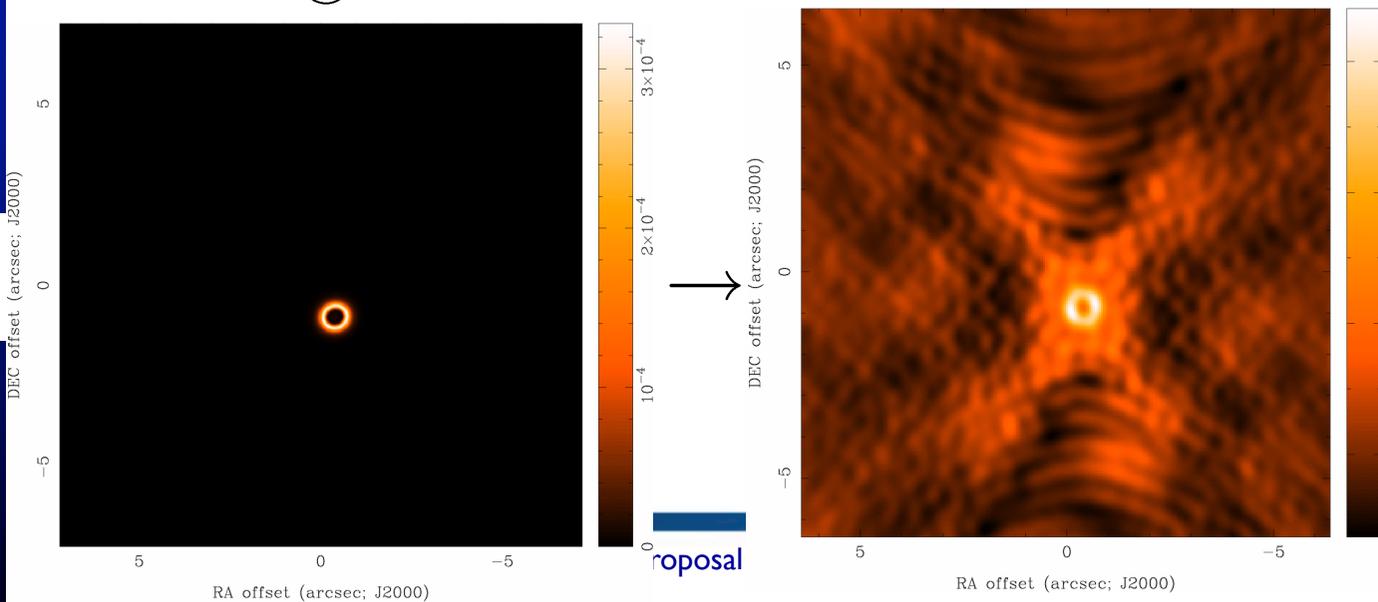
Visibility vs. Image (from NAASC Memo #104)

$B(x,y)$



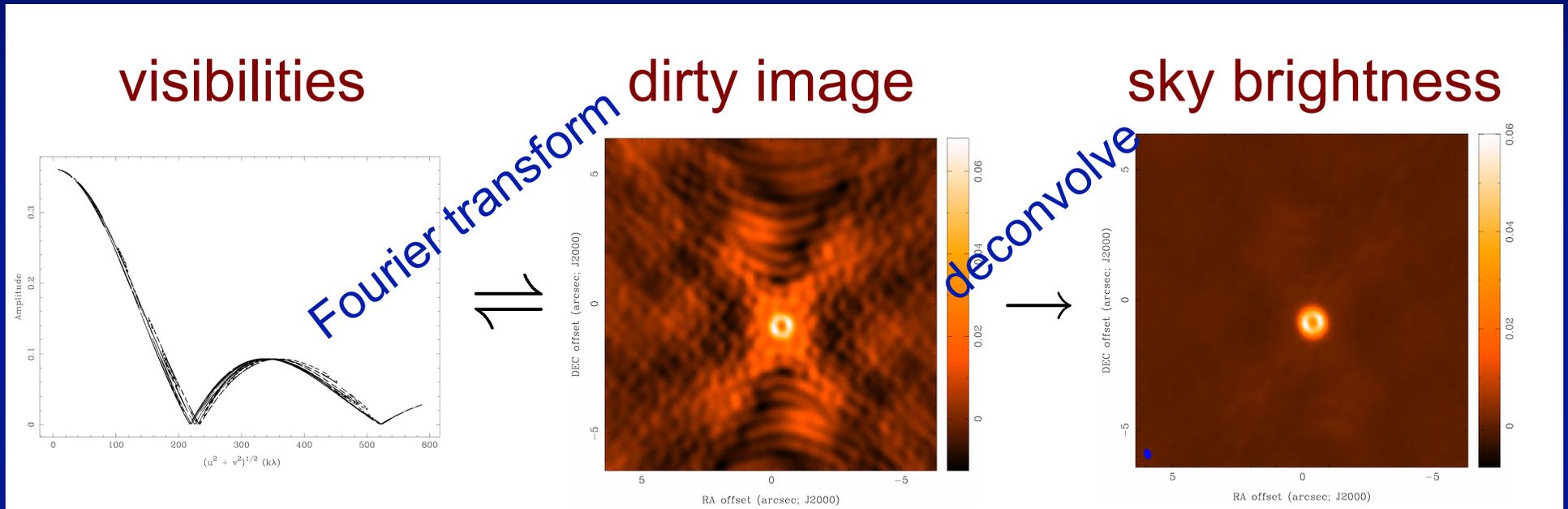
$S(u,v)$

$T(x,y)$



Dirty Image

Visibility → Dirty Image → Deconvolved Image (from NAASC Memo #104)



Deconvolution Method

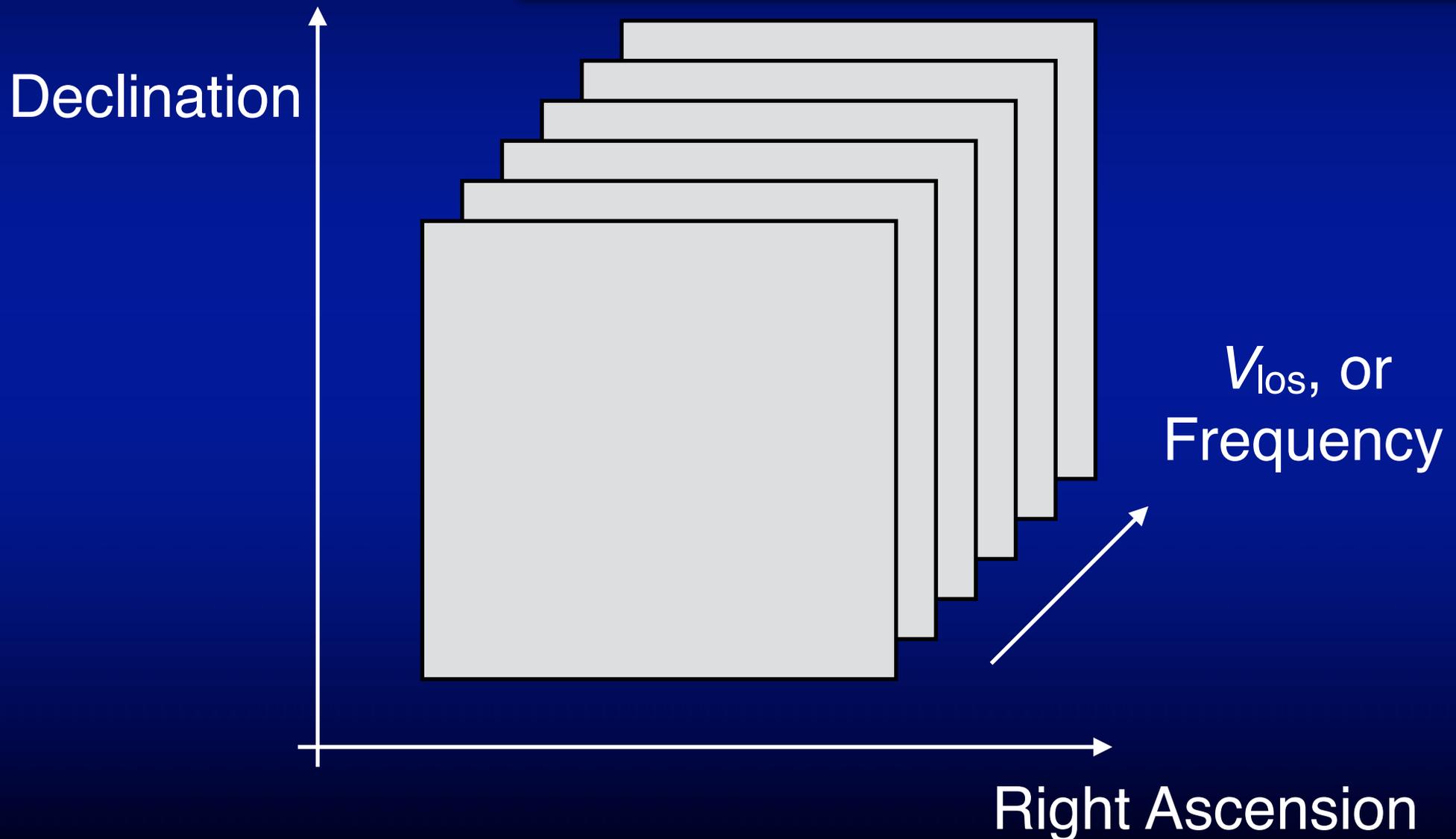
CLEAN

MEM

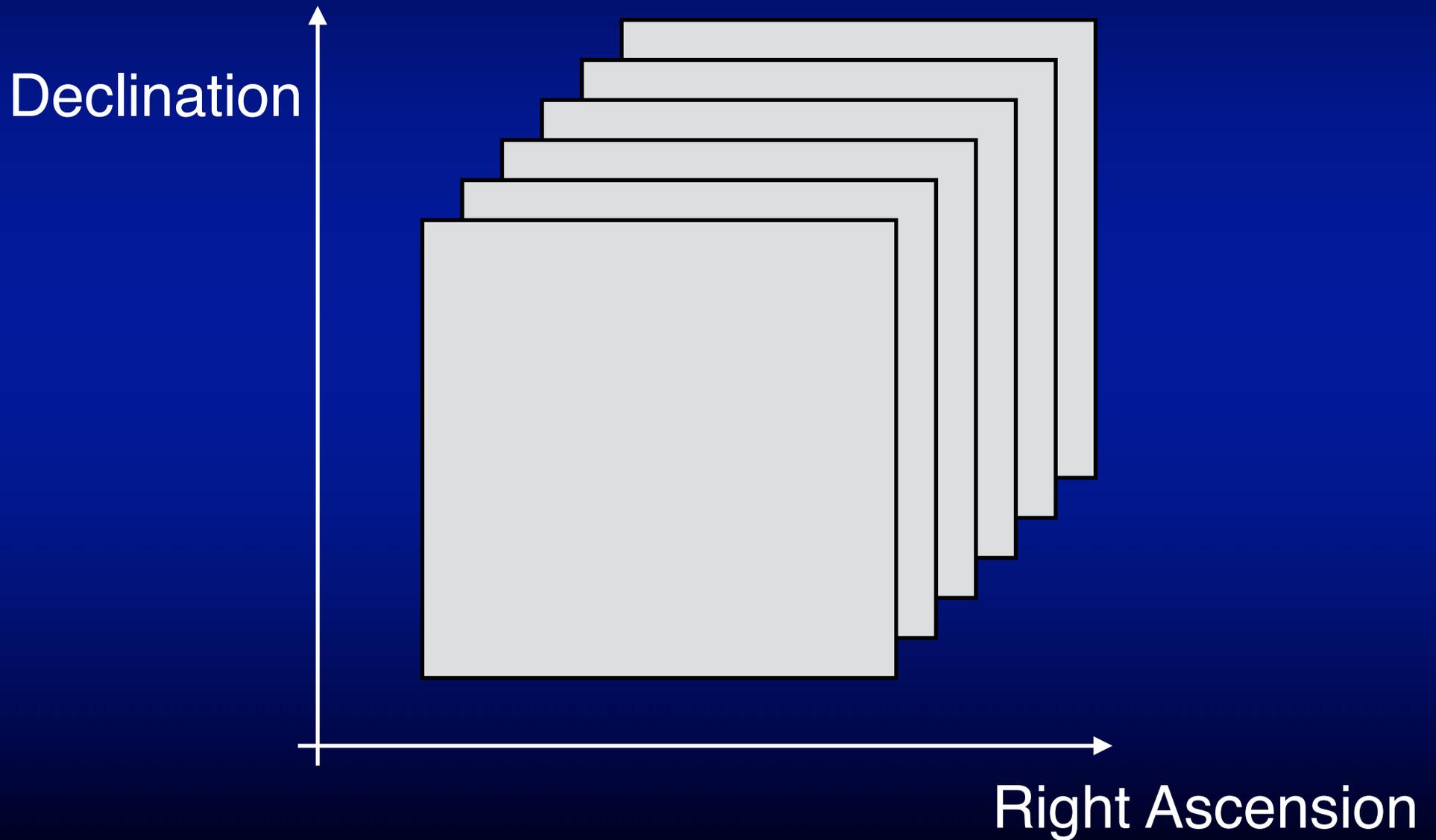
Data Cube

$$T(x, y, \nu), \text{ or } T(\alpha, \delta, v_{\text{los}})$$

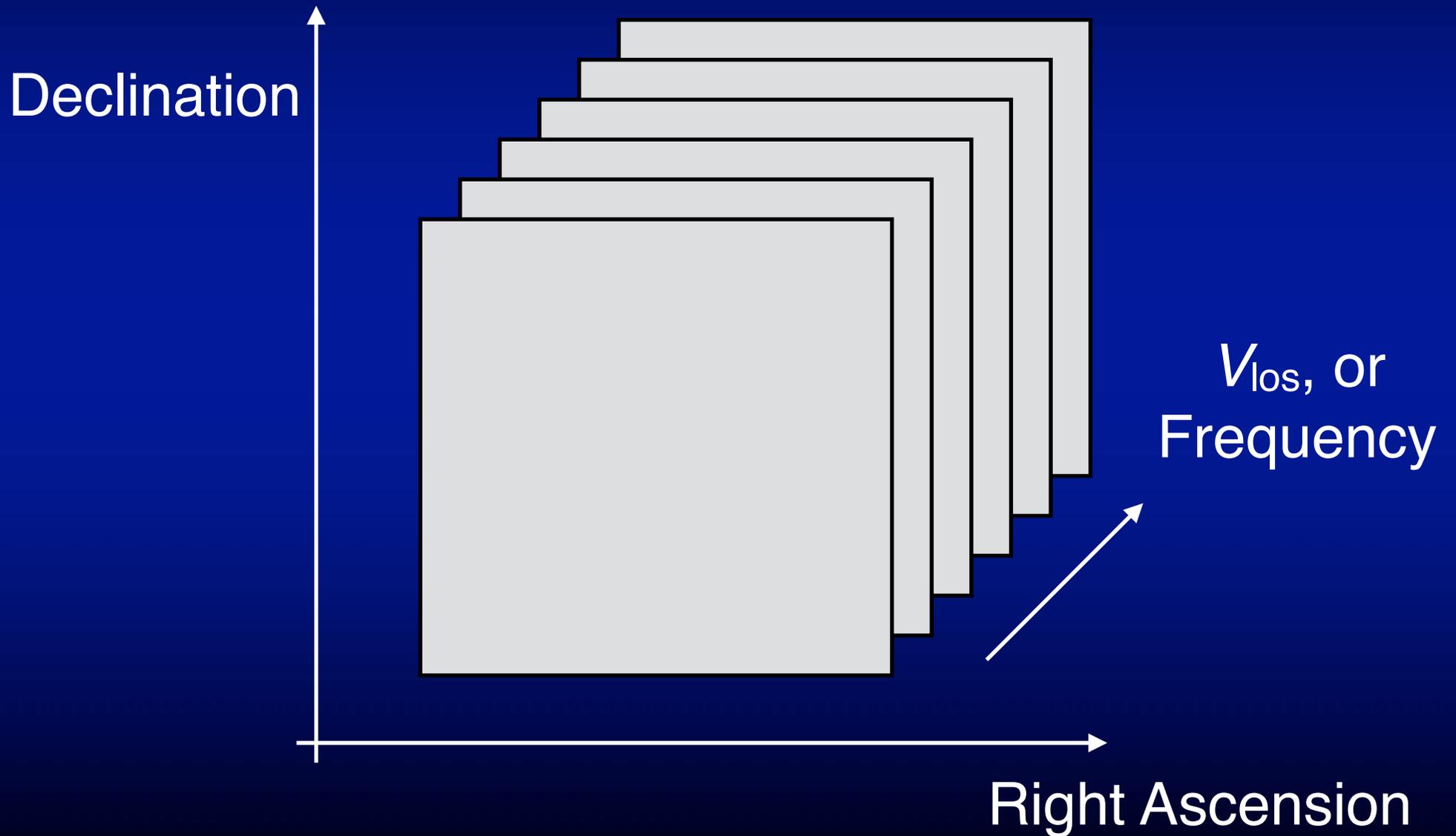
v_{los} is measured in “Local Standard of Rest” (LSR).



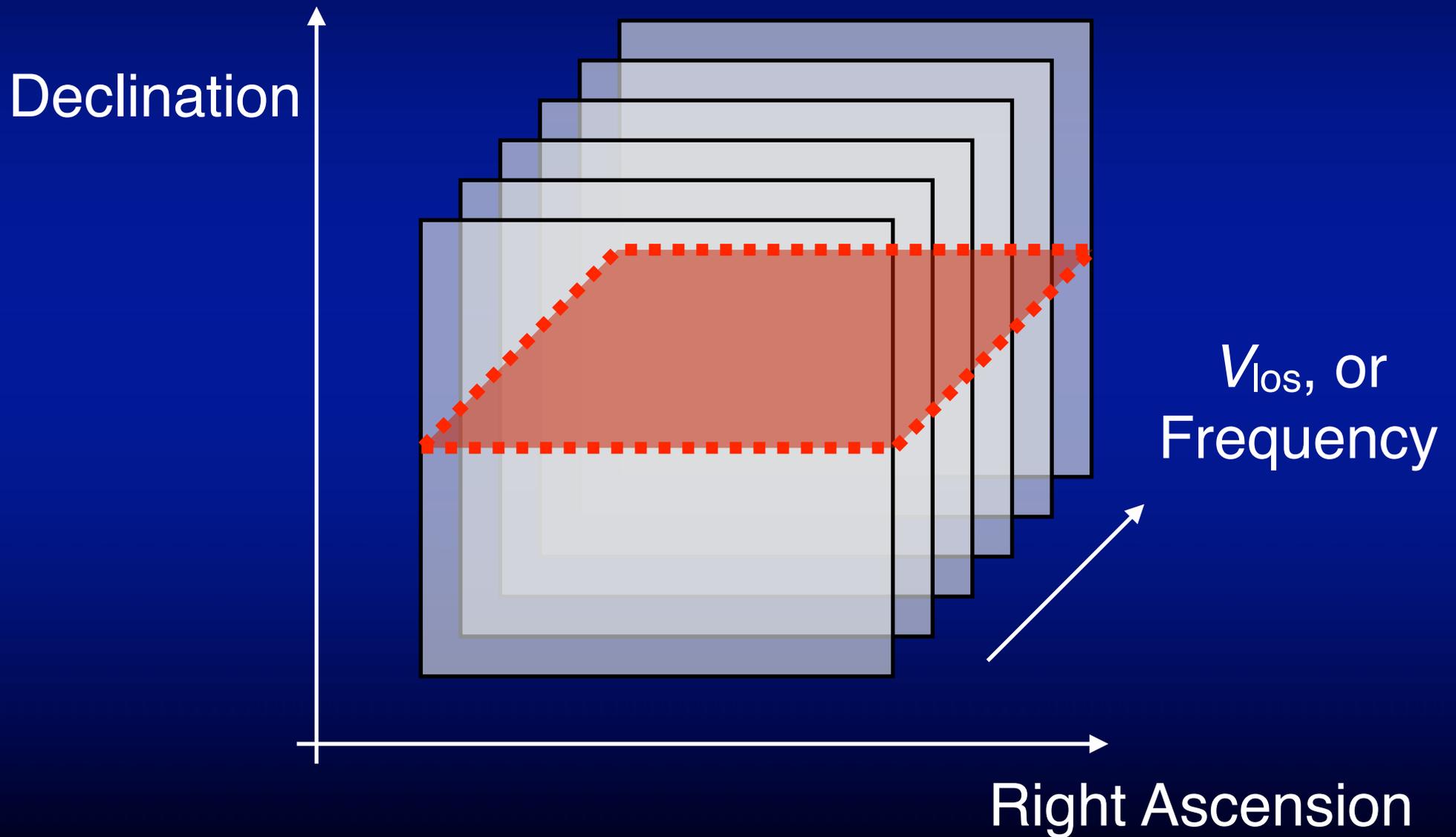
Channel Maps



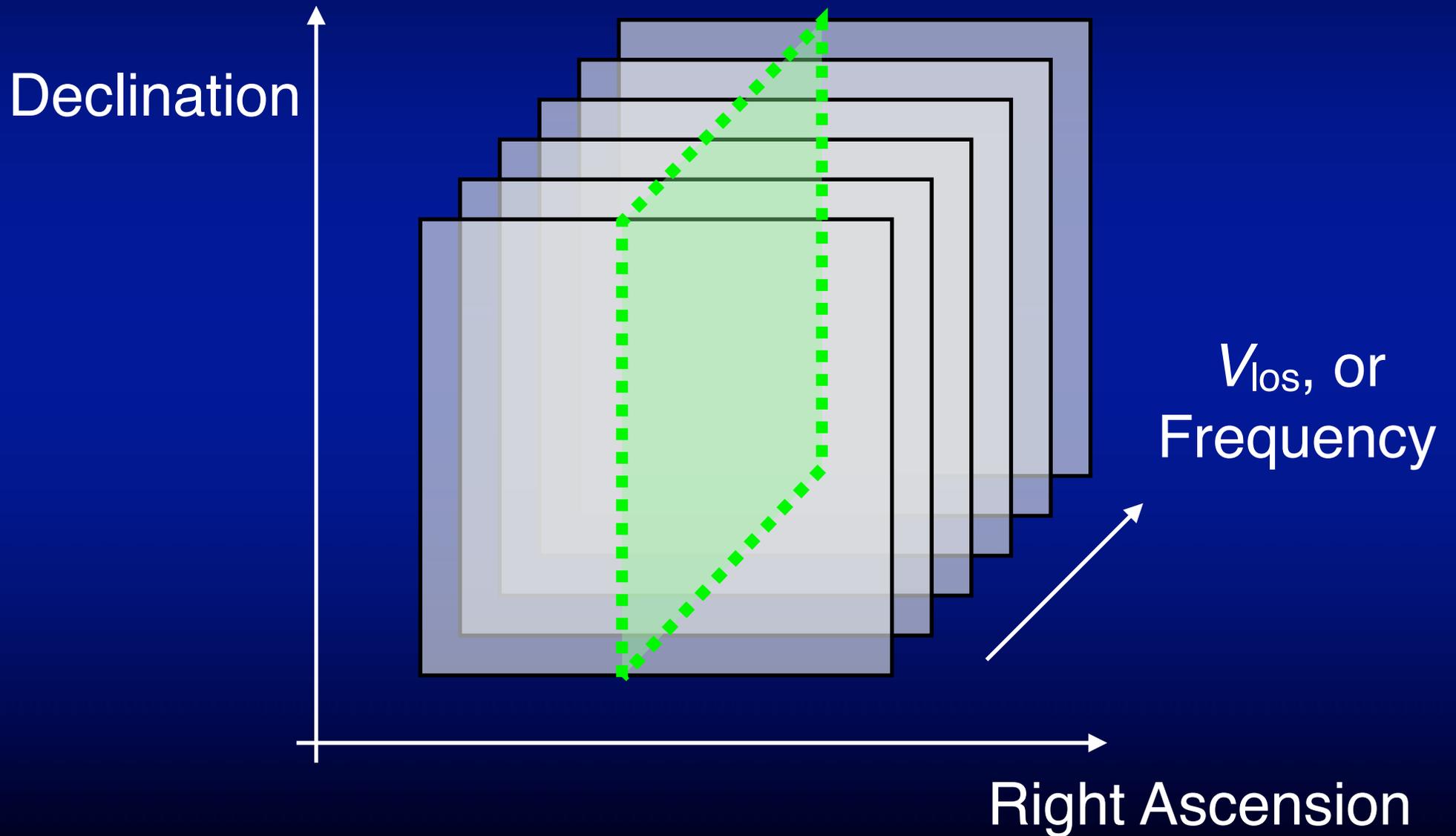
PV Diagram



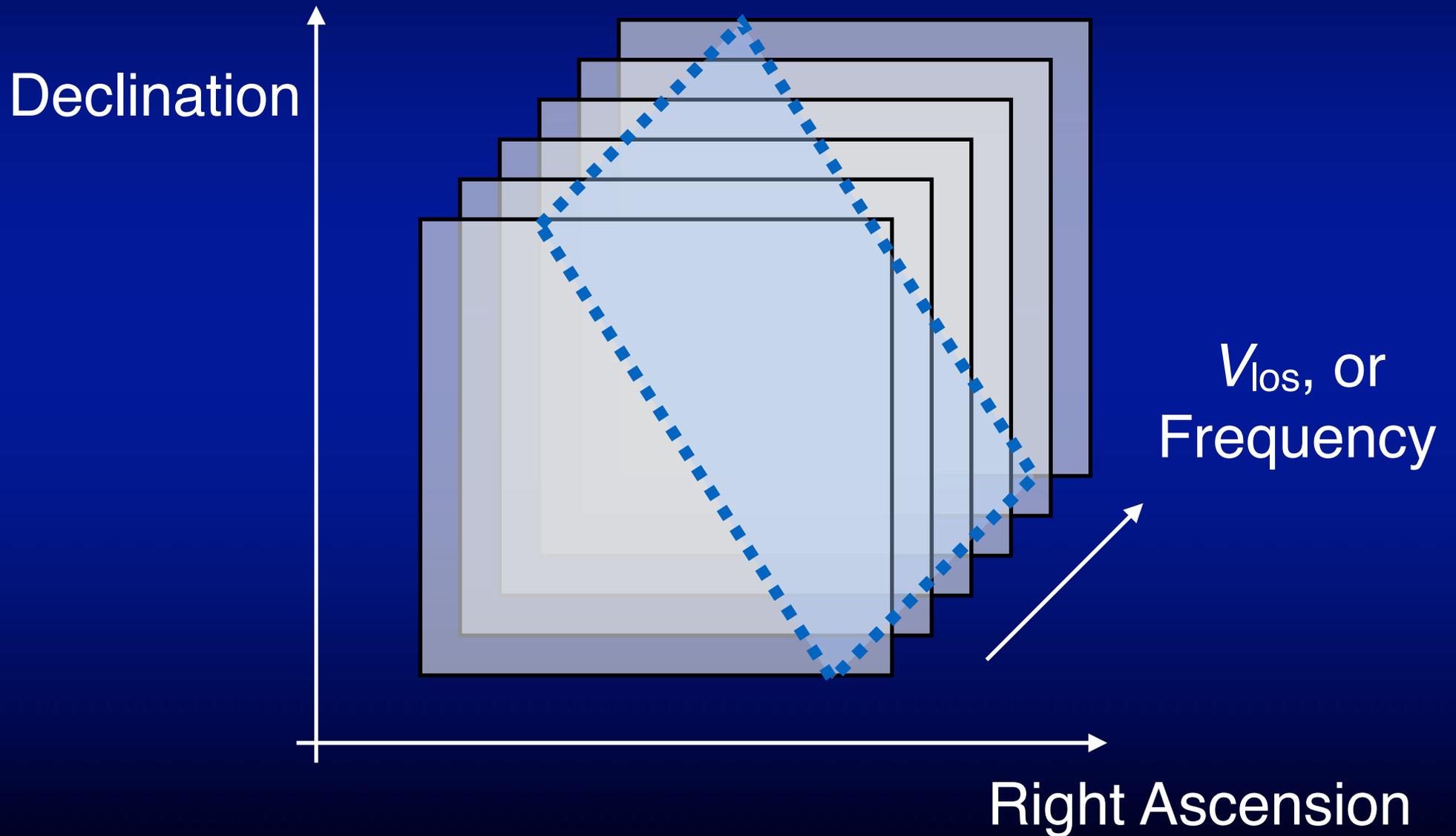
PV Diagram



PV Diagram



PV Diagram



Moment Maps

※ 以下はすべて場所(α, δ)ごとで計算

$$0\text{th: } I \equiv \int T(v) dv$$

積分強度

$$1\text{st: } \bar{v}_{\text{los}} \equiv \frac{\int v \cdot T(v) dv}{I}$$

平均速度

$$2\text{nd: } \Delta v \equiv \sqrt{\frac{\int (v - \bar{v}_{\text{los}})^2 \cdot T(v) dv}{I}}$$

速度分散

局所的なもの
(乱流・熱速度)

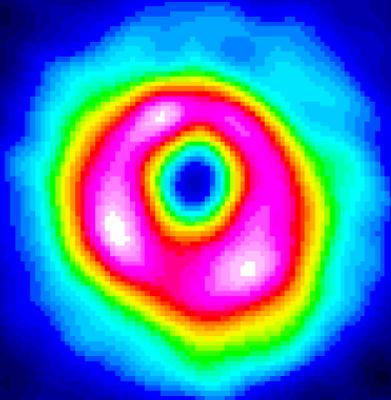
$$= \sqrt{\frac{\int v^2 \cdot T(v) dv}{I}} - \bar{v}_{\text{los}}$$

+
ビーム内速度勾配

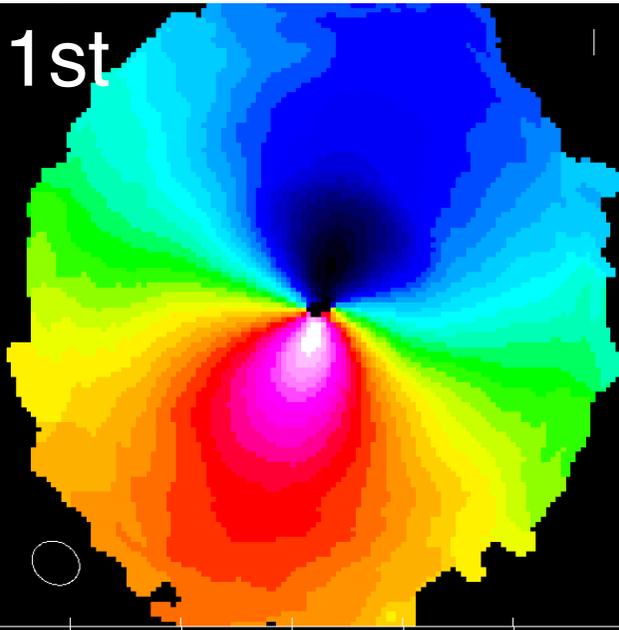
Examples: HD142527 in ^{13}CO (J=3-2)

Briggs Wt (upper) and Uniform Wt (lower)

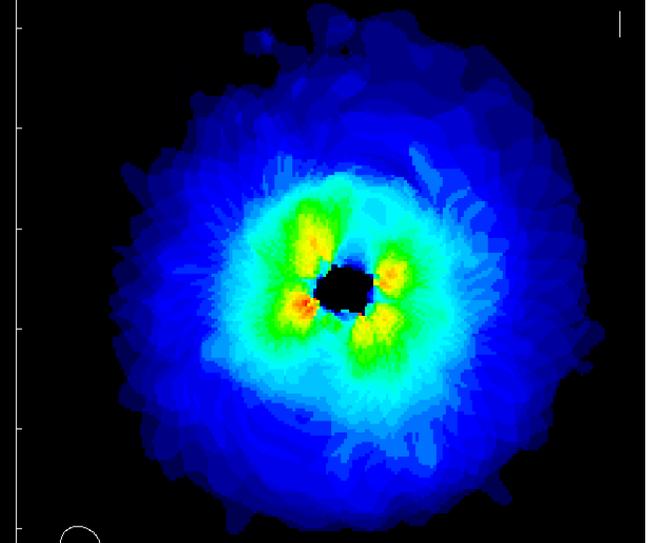
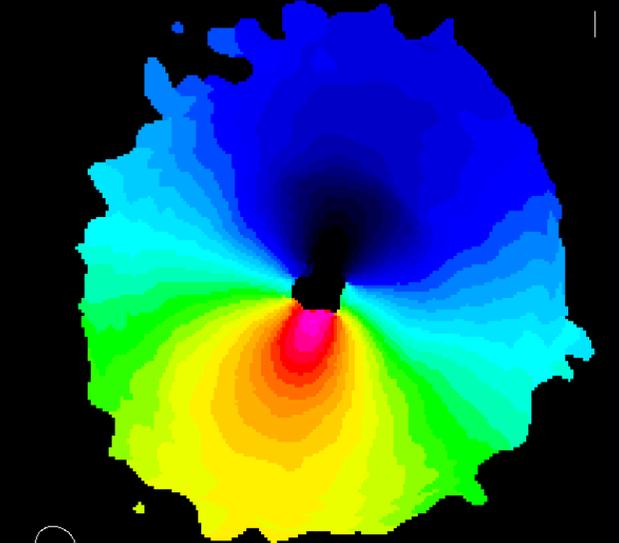
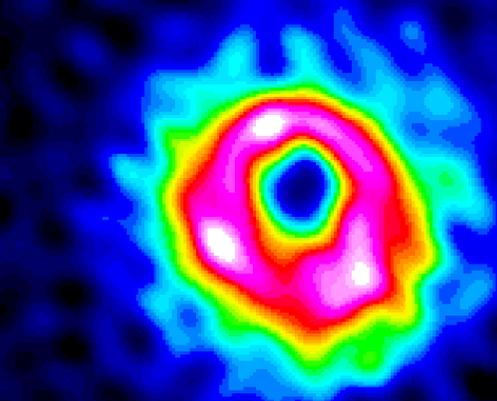
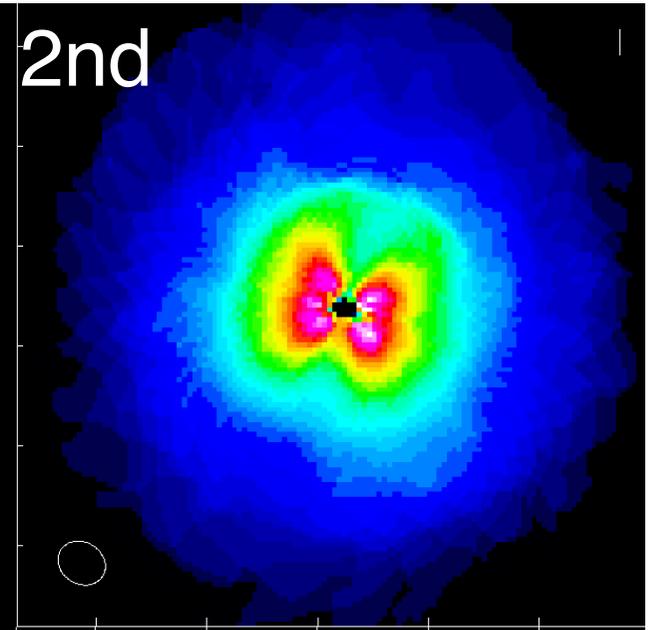
0th



1st



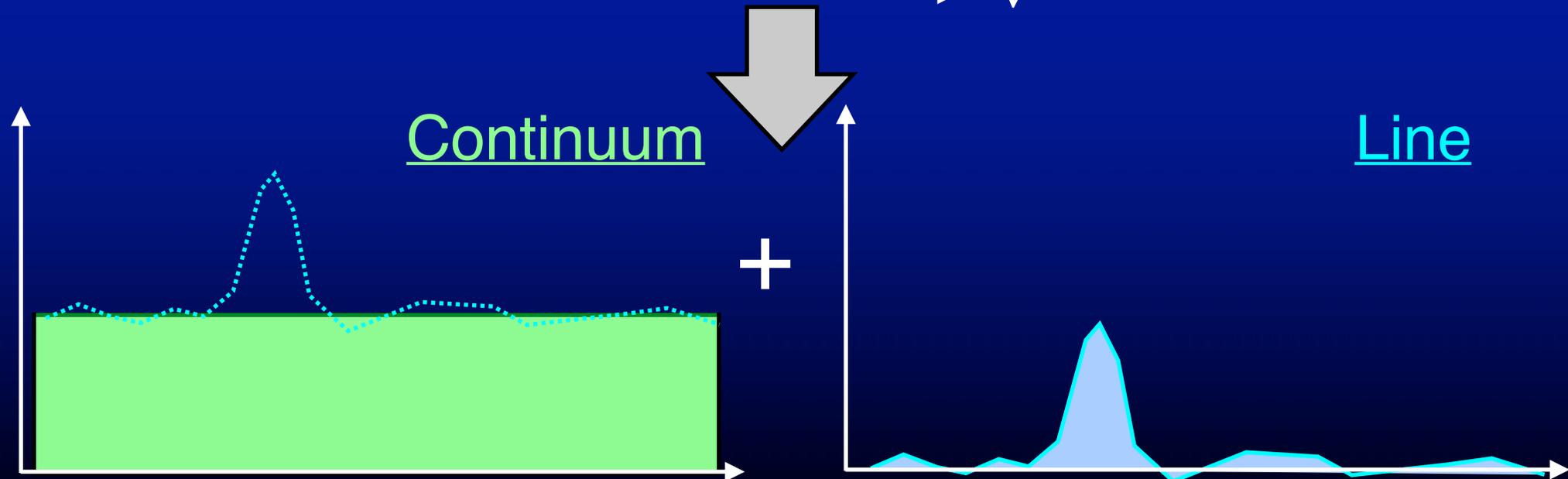
2nd



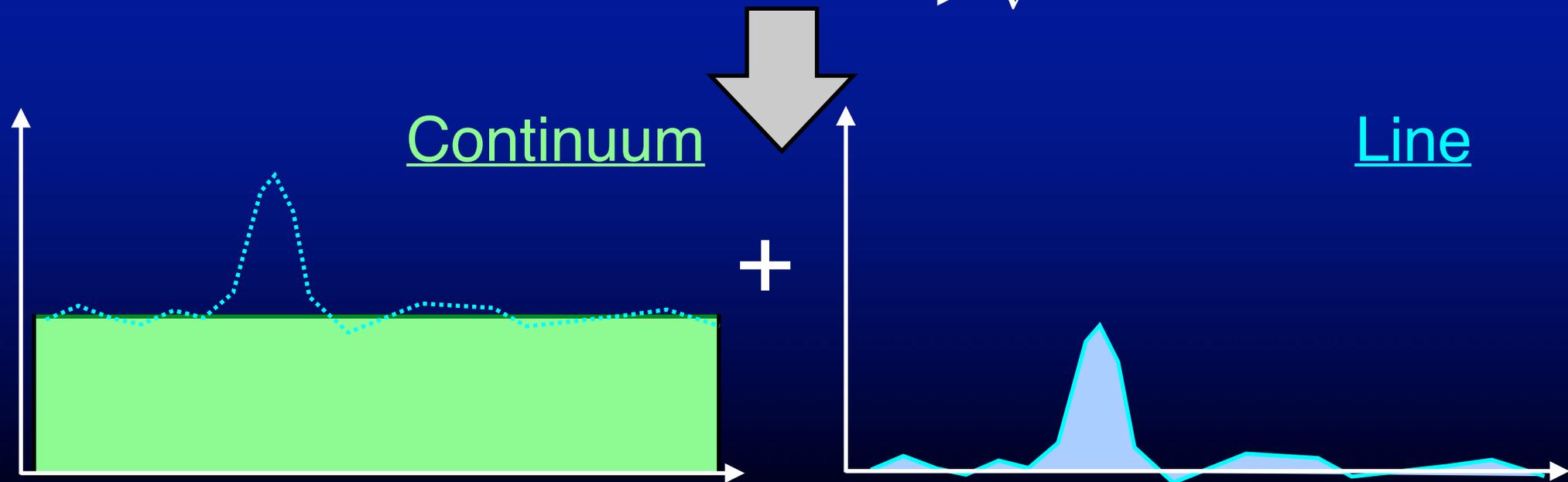
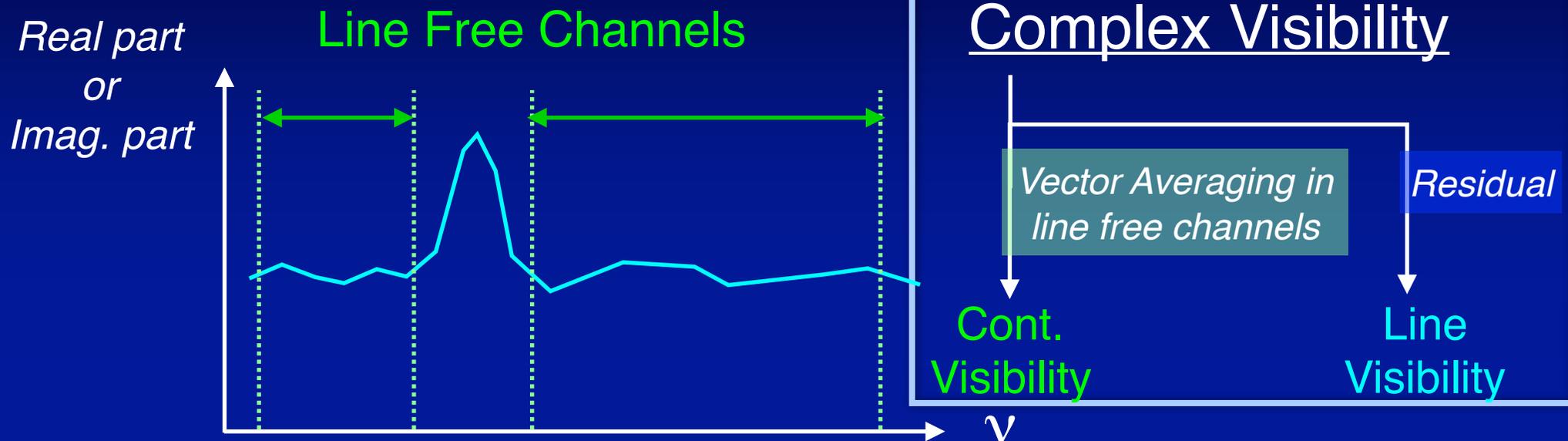
Continuum Subtraction



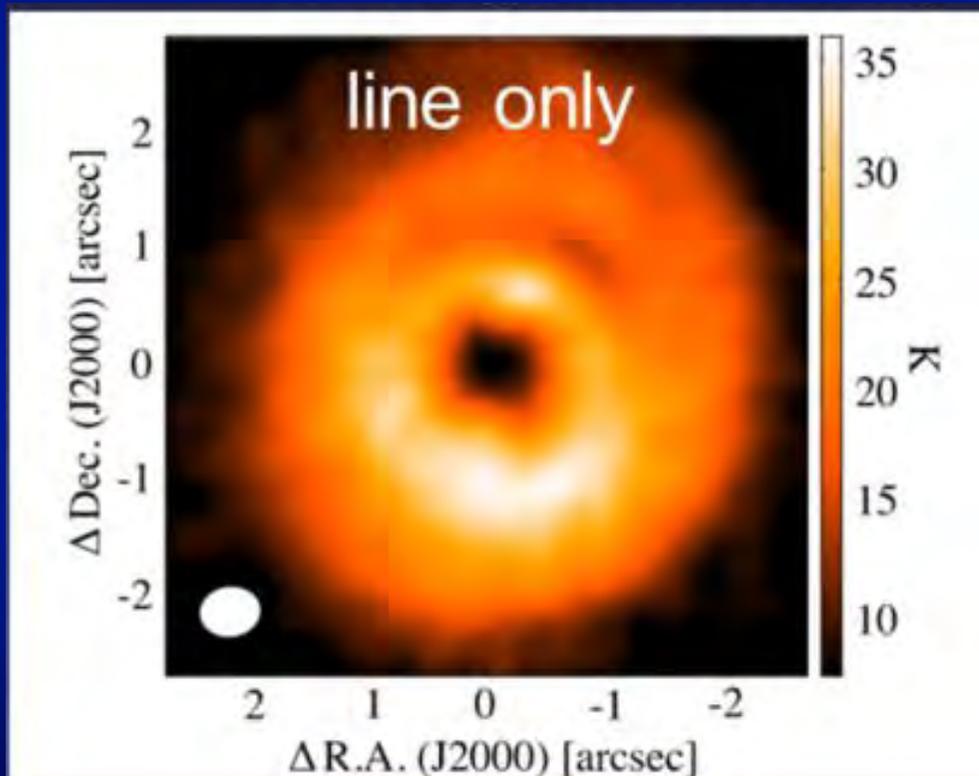
Simple Spectroscopy



Continuum Subtraction



Peak T_b map of ^{13}CO ($J=3-2$) around HD142527: Line only and Cont. added

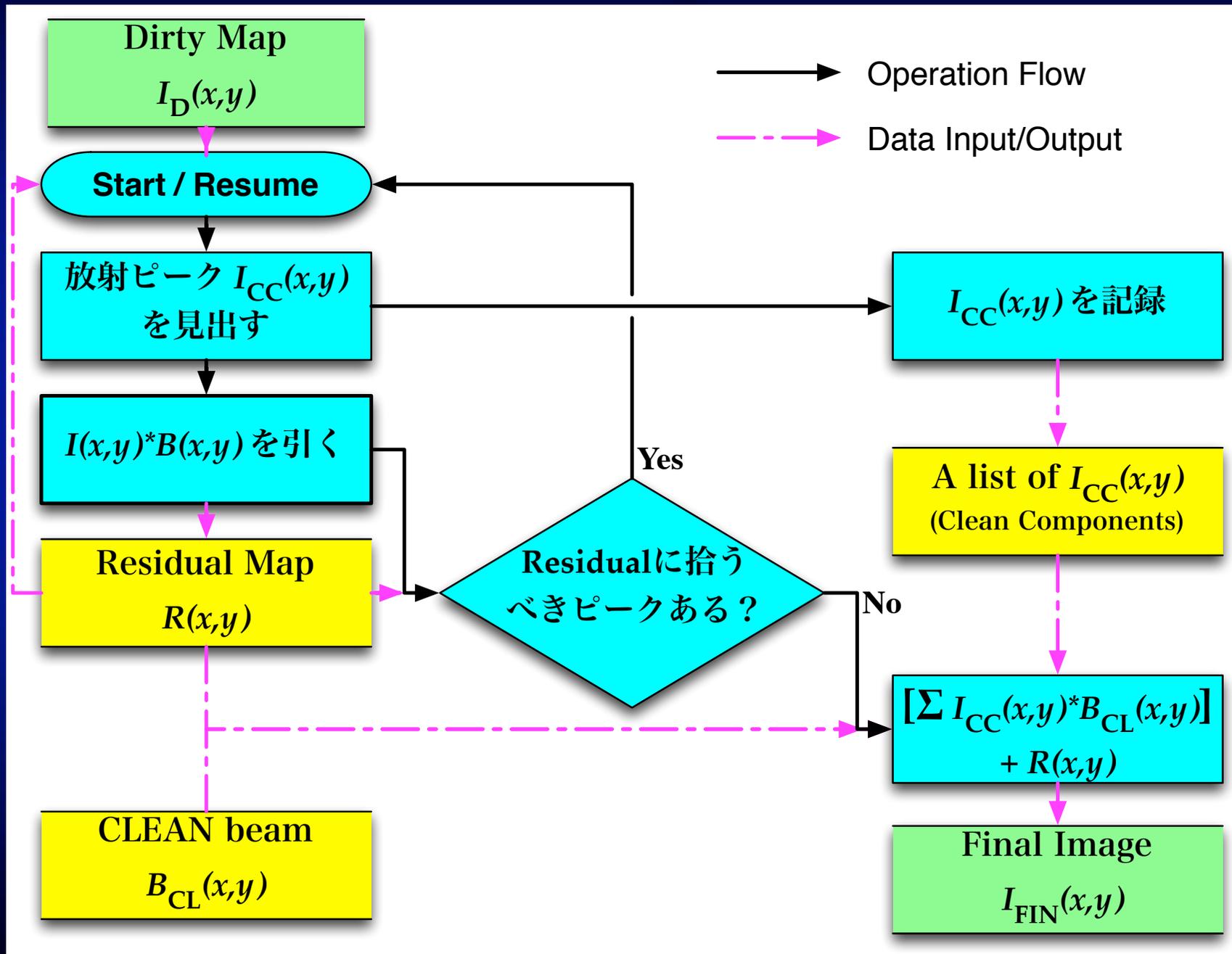


... in different color code

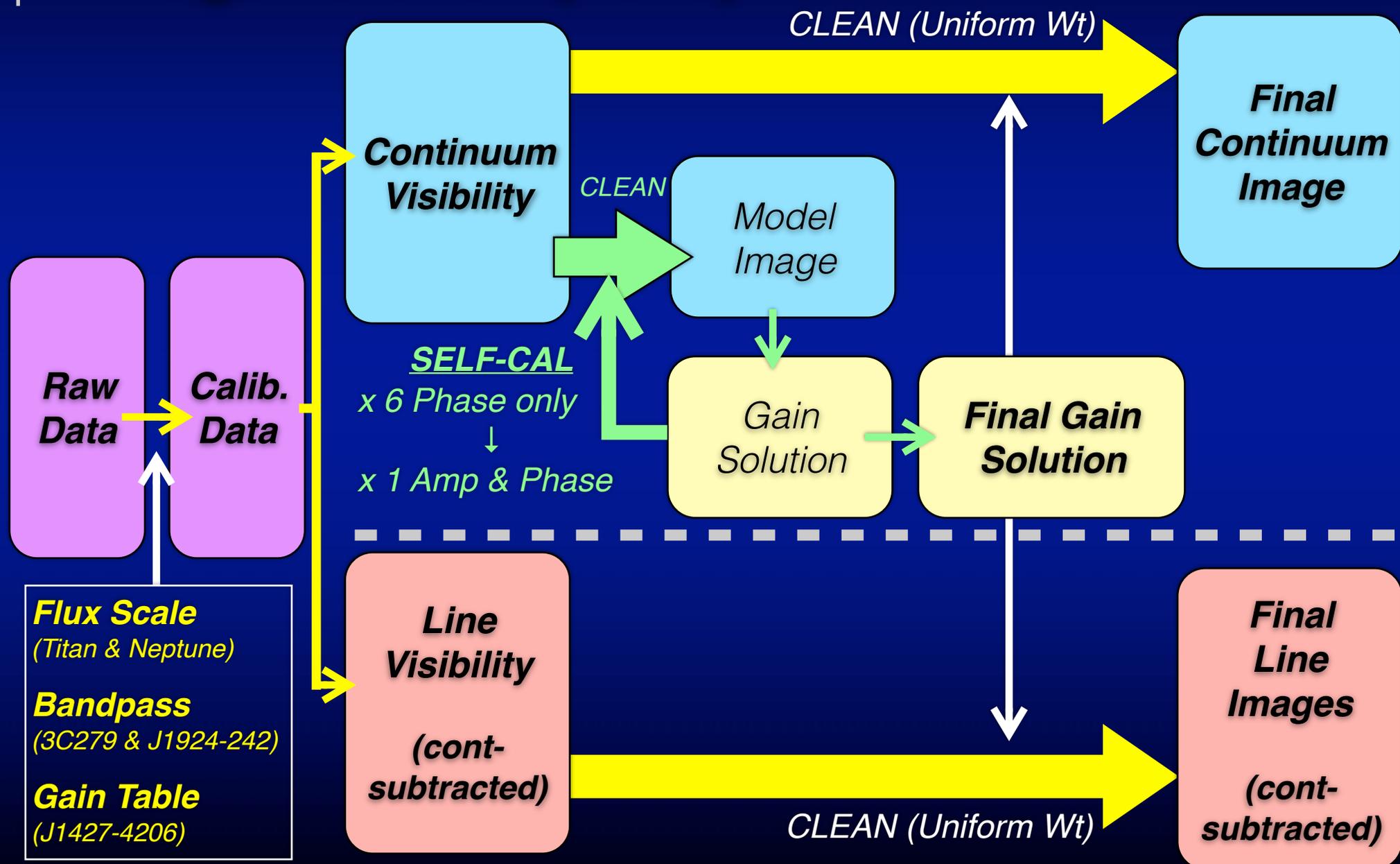
Continuum in grey lines

Advanced Materials

CLEAN Algorithm



Data Reduction in the case of Fukagawa et al. (2013)



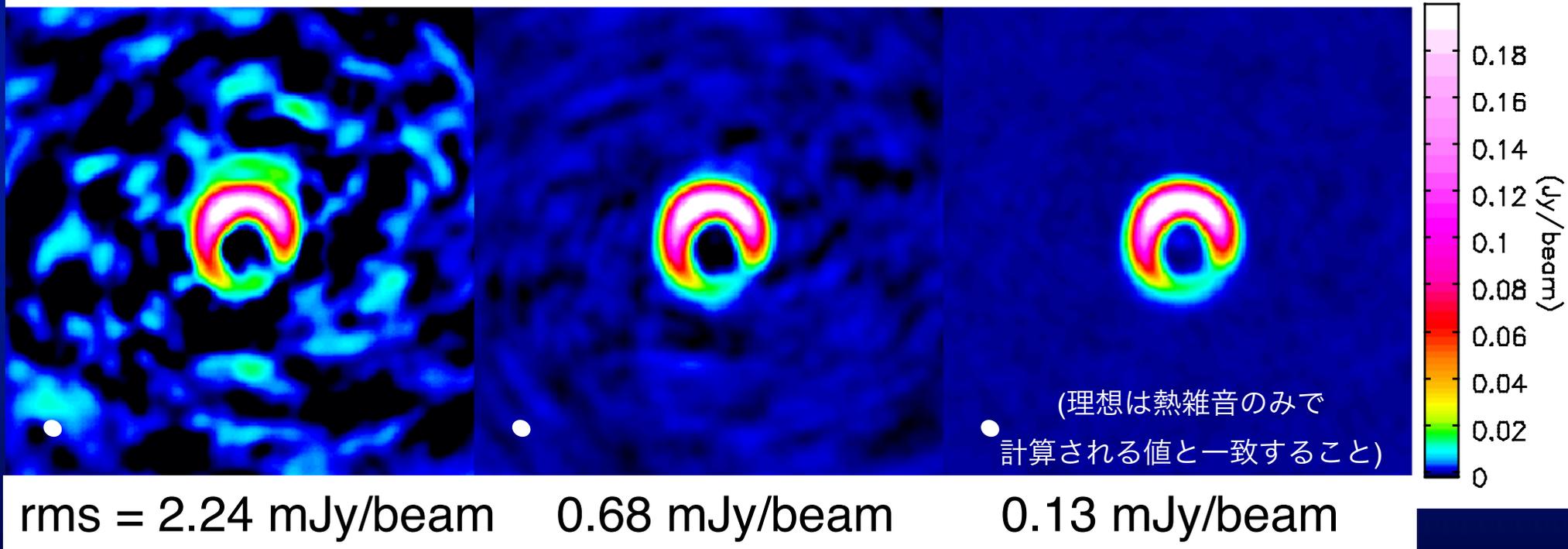
Self-Calibration: “Before-After”

HD142527 Continuum @ 330 GHz

Before Self-Cal.

after
1 iteration
solving phase only

Final Image
6 iterations
solving phase +
1 iteration
solving amp. & phase



※ 少しずつ慎重に（やり過ぎると1箇所放射を集める場合あり）

※ 独立した偏波成分を取得する受信機同士でconsistentな解を示しているか

Self-Calibration

明るくコンパクト

瞬時瞬時のVisibility Phaseを
支配。予測可能。

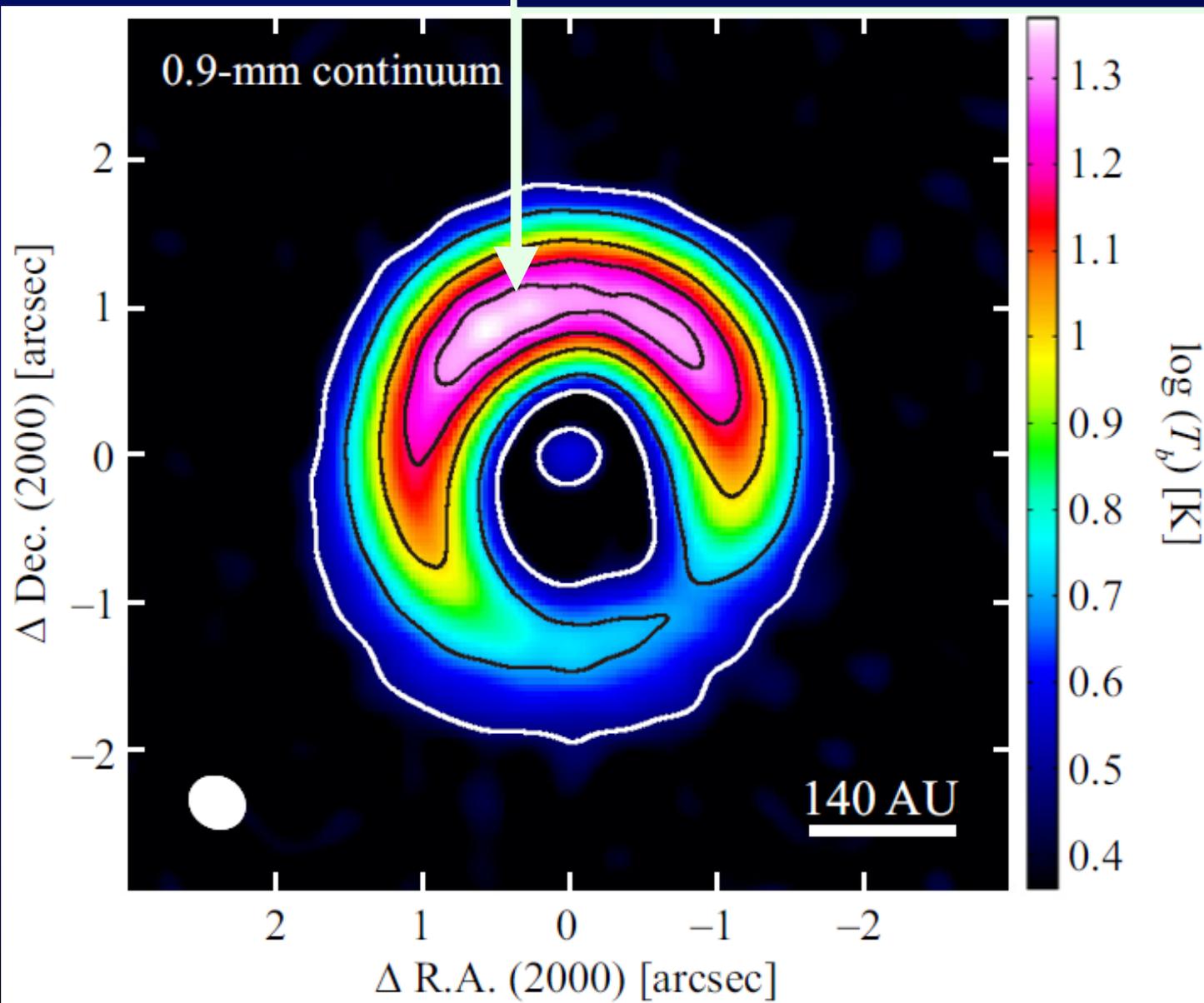
$$N_{\text{ant}} < N_{\text{baseline}}$$



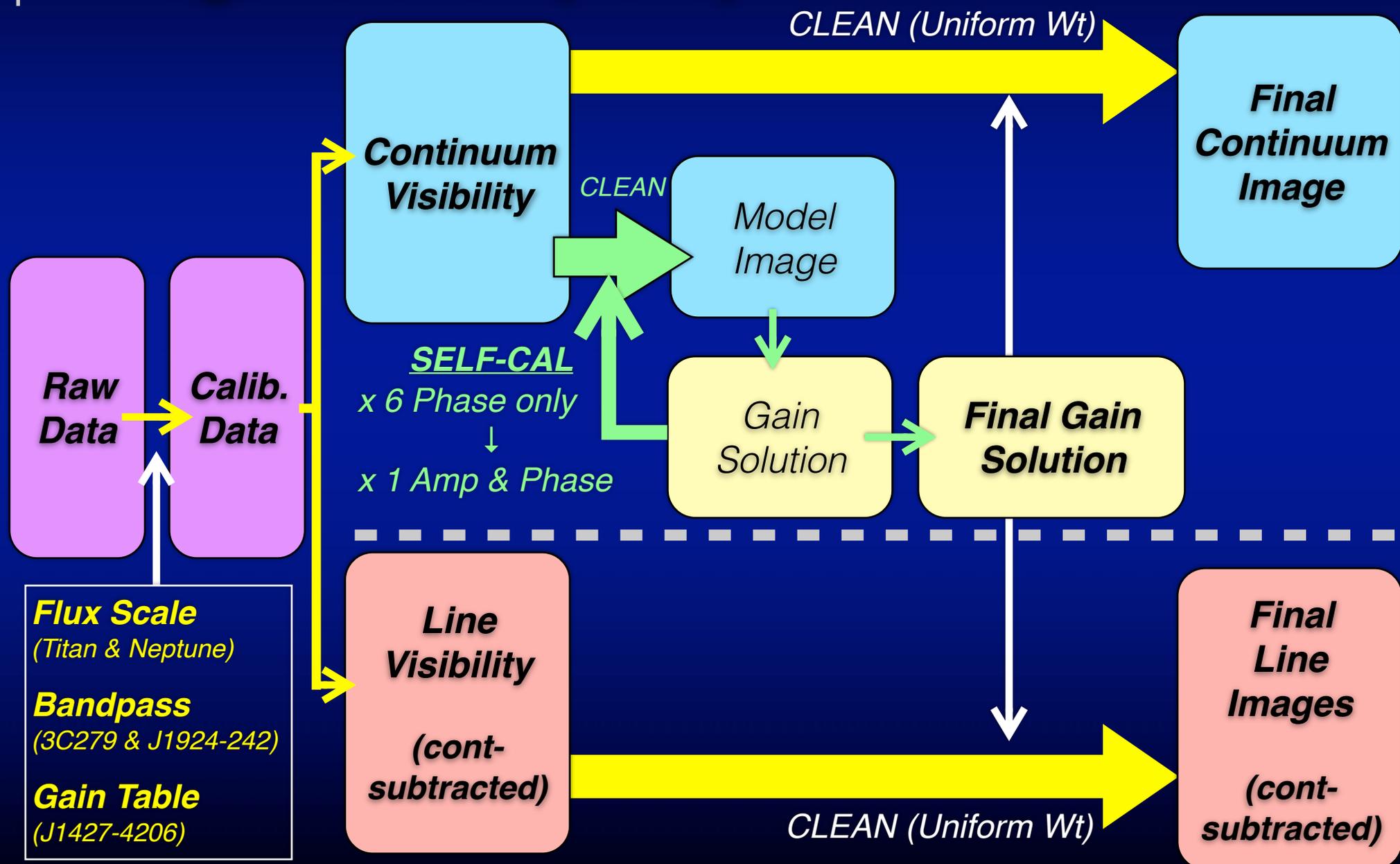
アンテナベースの
位相誤差

(大気水蒸気の揺らぎ,
装置の位相揺らぎ等)
を解くことができる

(モデルイメージの
解との比較)



Data Reduction in the case of Fukagawa et al. (2013)



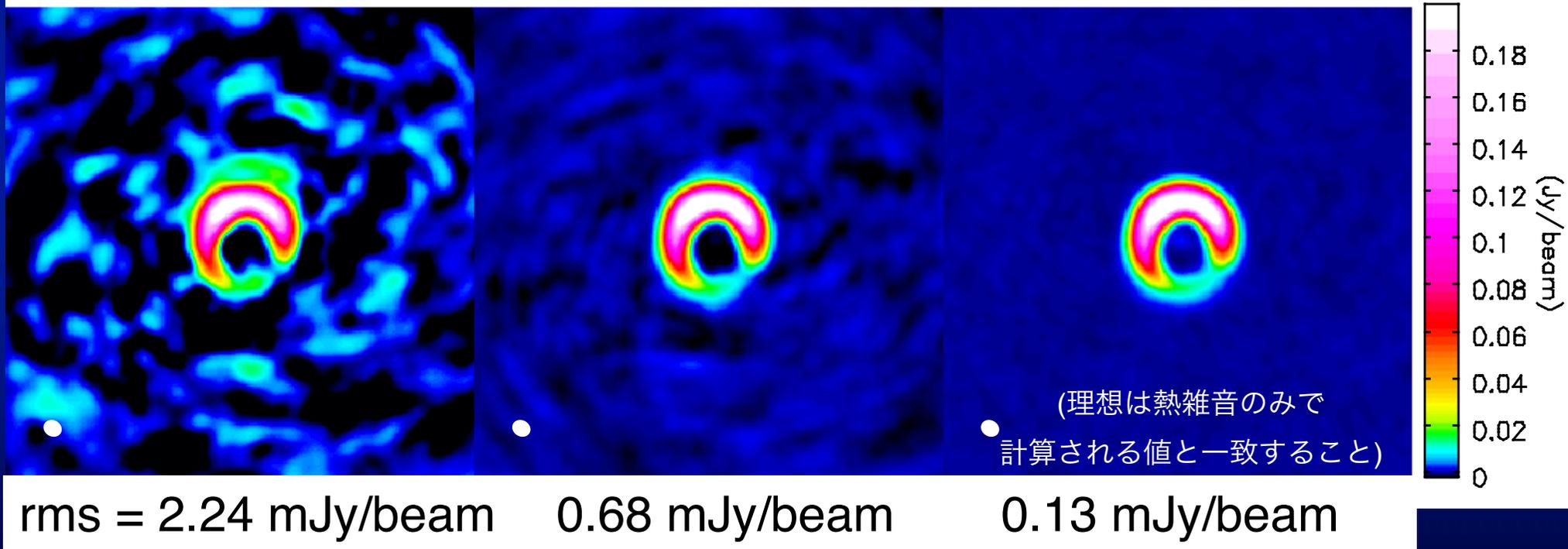
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